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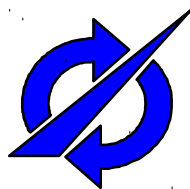
# Ontology-Based Robots Self-Organization in Cyber-Physical Systems

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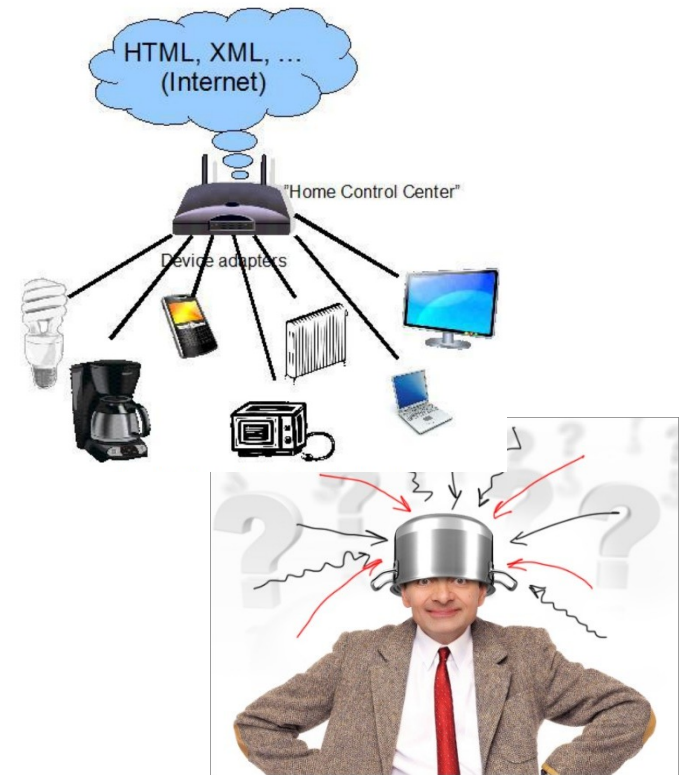
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# Motivation



- Increasing number of devices with built-in processors and data storage possibilities (more than **50 billions** of devices, more than **5 billions** of smartphones will be available in **10 years**).
- **Device interaction** technologies which allows to achieve **maximum profit**: Internet of Things (IoT), World Wide Sensor Network, Smart Building Environment, and etc.
- Limitation of **cognitive human abilities**, which progress slowly than computers (usually at the moment human can not keep in mind all information he/she need for making decisions).

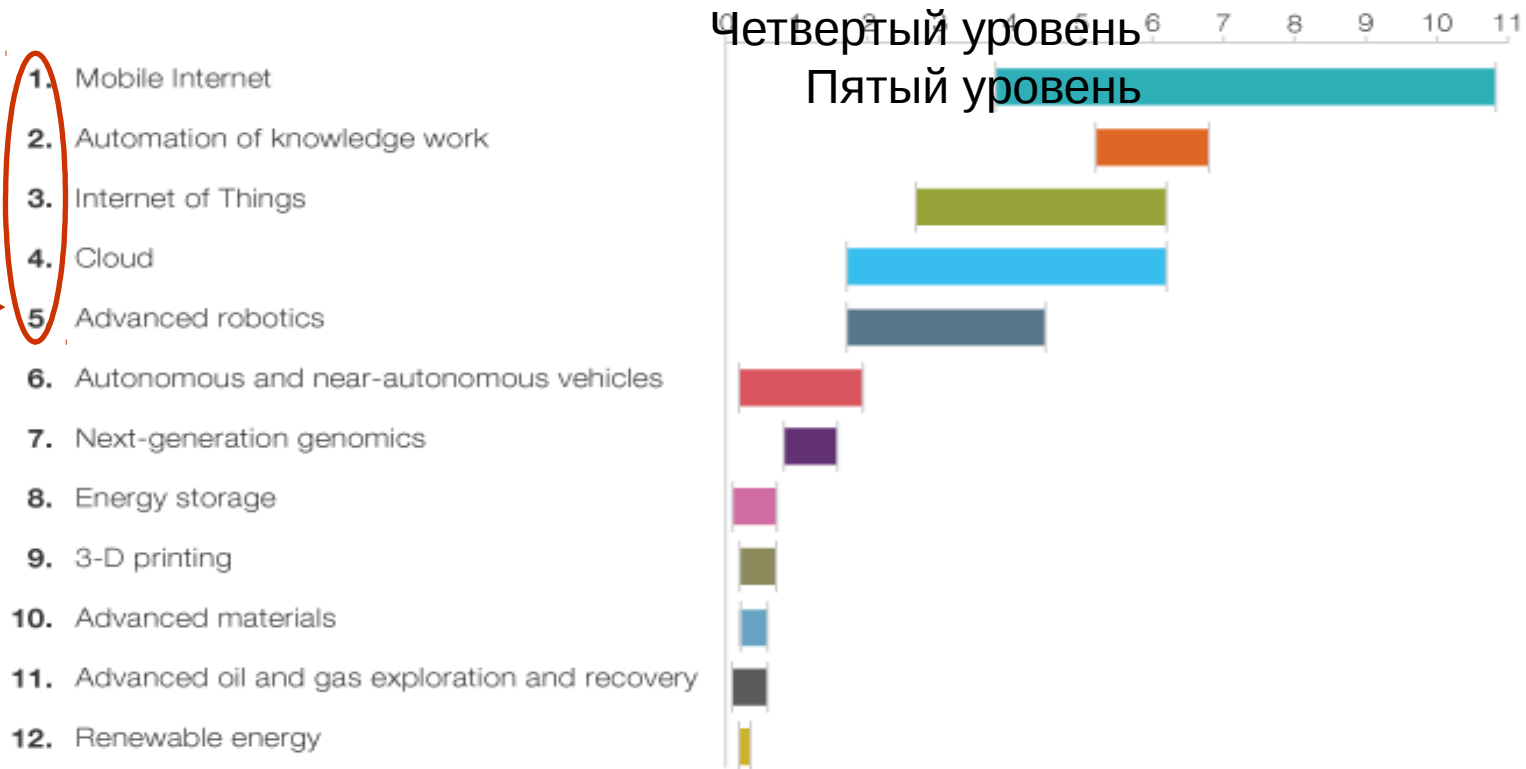


# Top 12 Technologies by McKinsey Global Institute (May 2013)



## A gallery of disruptive technologies

Estimated potential economic impact of technology applications in 2025, \$ trillion, annual



Source: McKinsey Global Institute, Report MGI “Disruptive technologies: Advances that will transform life, business, and the global economy” (May 2013). [http://www.mckinsey.com/insights/business\\_technology/disruptive\\_technologies](http://www.mckinsey.com/insights/business_technology/disruptive_technologies)

# Modern Technologies



## Mobile Internet

Increasingly inexpensive and capable mobile computing devices and Internet connectivity



## Automation of knowledge work

Intelligent software systems that can perform knowledge work tasks involving unstructured commands and subtle judgments



## The Internet of Things

Networks of low-cost sensors and actuators for data collection, monitoring, decision making, and process optimization



## Cloud computing

Use of computer hardware and software resources delivered over a network or the Internet, often as a service



## Advanced robotics

Increasingly capable robots with enhanced senses, dexterity, and intelligence used to automate tasks or augment humans

# Cyber-Physical Systems (CPS)



Cyber-physical systems are **physical and engineered systems** whose operations are integrated, monitored, and/or **controlled** by a **computational core**. Components are **networked** at every scale. Computing is deeply embedded into every physical component, possibly even into materials. The computational core is an embedded system, usually demands **real-time response**, and is most often distributed.



*Helen Gill, NSF, USA*

Cyber-Physical Systems or “smart” systems are co-engineered **interacting networks of physical and computational components**. These systems will provide the foundation of our critical infrastructure, form the basis of emerging and future smart services, and **improve our quality of life in many areas**.

National Institute of Standards and Technology, USA

# Cyber-Physical-Social Systems (CPSS)

- CPSS in contrast with CPS consist of not only **cyberspace** and **physical space**, but also **human knowledge**, **mental capabilities**, and **sociocultural elements**.

## Social Networks

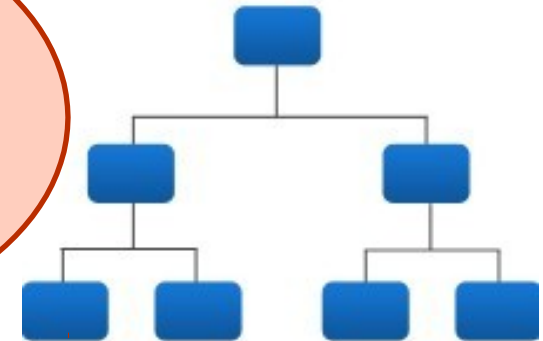


## Physical world



Cyber-Physical-Social Systems

## IT world





# Example of CPSS



© John Deere

Communication



Communication harvester – back-office

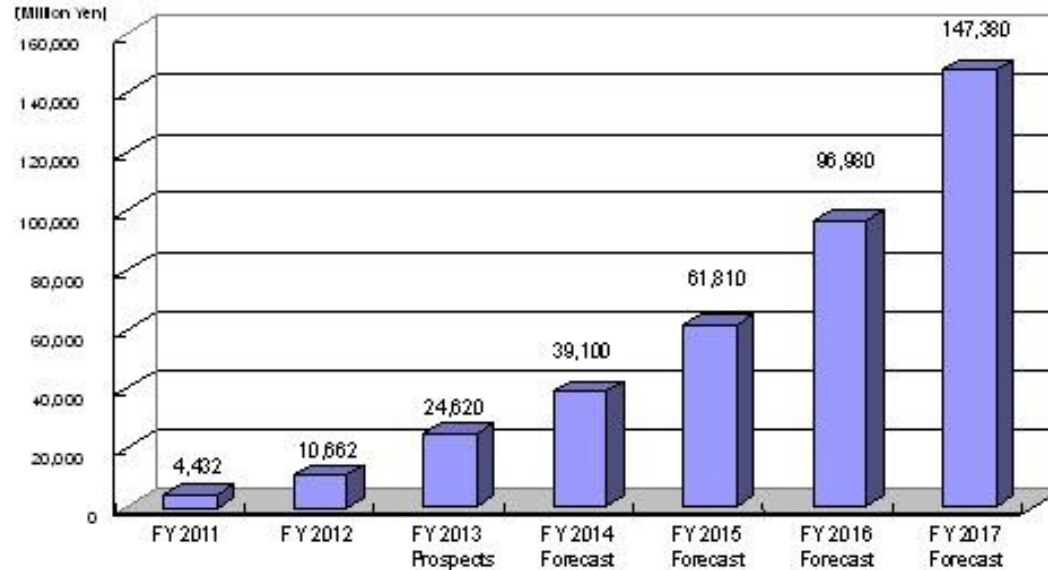
- Cut tree; measure length, diameter, wood quality.
- Check markets prices and customer orders.
- Decide on usage of the tree (which product, what customer).
- Cut according to back-office decision and mark product.



# Crowdsourcing



*“The act of a company or institution taking a **function** once **performed** by **employees** and **outsourcing** it to an undefined (and generally large) **network of people** in the form of an open call” (Jeff Howe\*)*

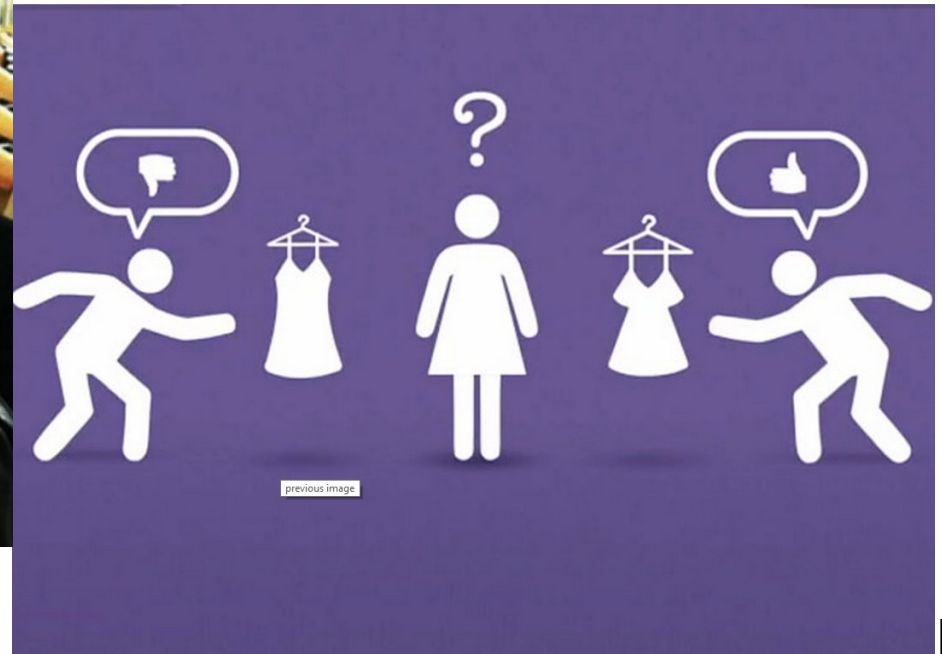


***Crowdsourcing market size in Japan\*\****

\*) Jeff Howe “Crowdsourcing: A Definition” [http://crowdsourcing.typepad.com/cs/2006/06/crowdsourcing\\_a.html](http://crowdsourcing.typepad.com/cs/2006/06/crowdsourcing_a.html)

\*\*\*) Yano Research Institute: <http://www.yanoresearch.com/press/press.php/001161>

# Example of Crowdsourcing-Based CPSS

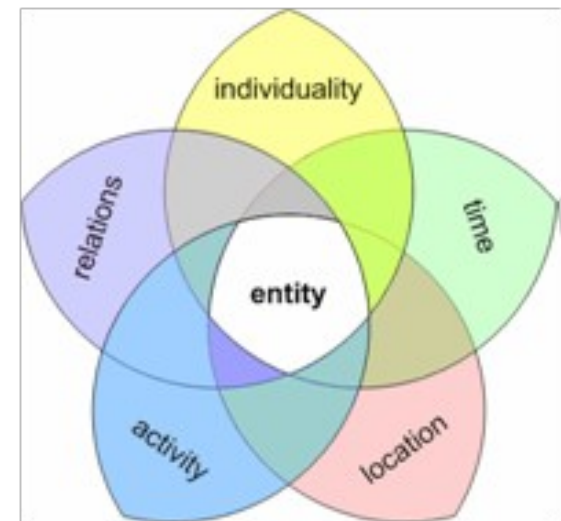


Can't decide which shirt to get? Let Facebook be the judge. C&A introduced a high-tech hanger that tallies the number of Facebook "likes" an item of clothing on its racks receives.

Source: <http://www.ecouterre.com/ca-debuts-clothes-hangers-that-display-facebook-likes-in-real-time/>

# Introduction: Context in CPSSs

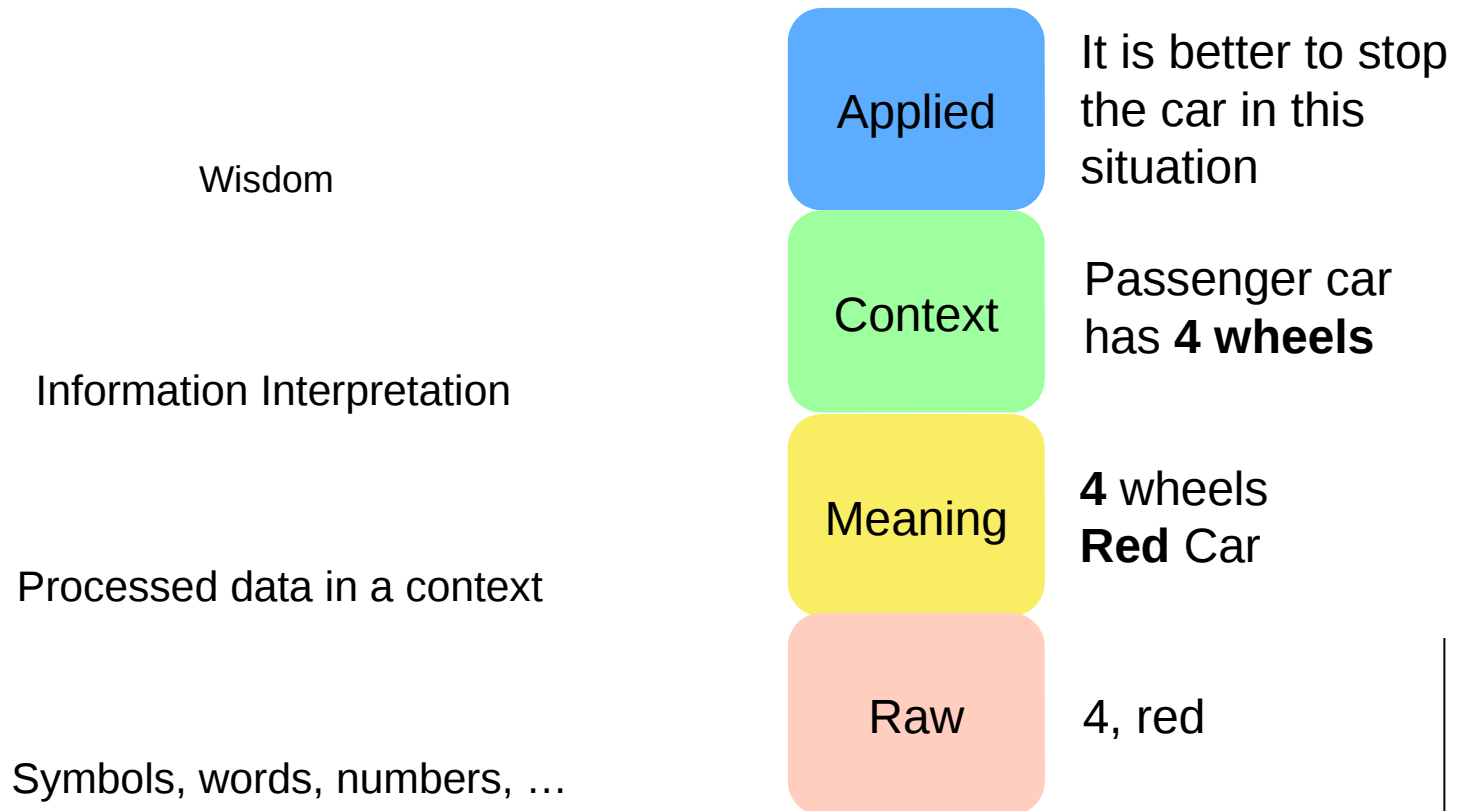
- CPSSs are expected to be context-aware.
- Context is any information that can be used to **characterize** the **situation** of an entity. An entity is a person, place or object that is considered relevant to the interaction between a user and an application, including the user and applications themselves [Dey et al. 2000].
- Context is described as an **ontology-based model** specified for actual settings. Multiple sources of data/information/knowledge provide information about the actual settings.



## Fundamental categories for context information

Zimmermann, A., Lorenz, A., Oppermann, R.: An Operational Definition of Context. In: Kokinov, B. et al. (eds.) CONTEXT 2007. LNAI, vol. 4635, pp. 558–571. Springer-Verlag, Berlin, Heidelberg (2007)

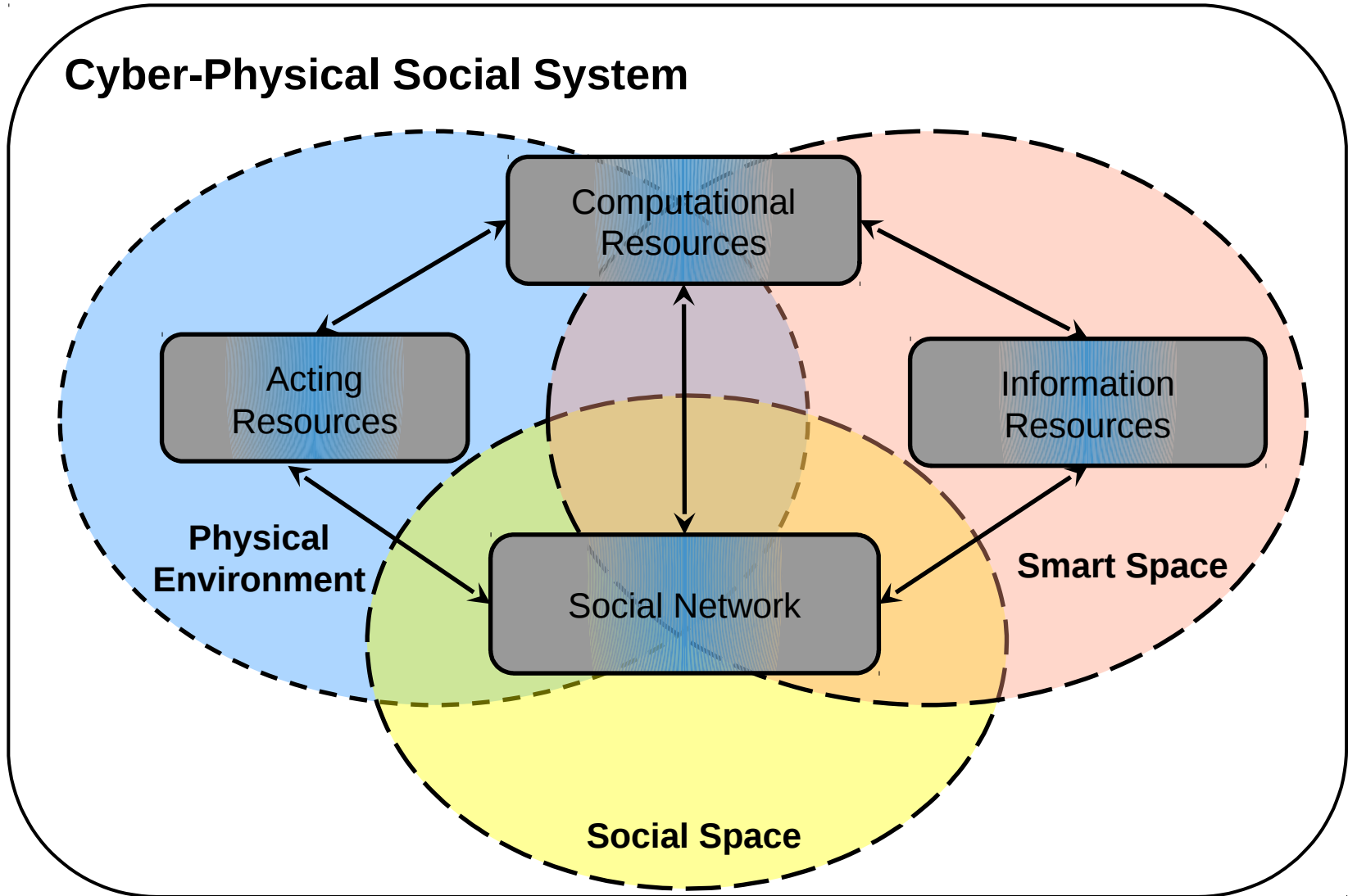
# Data, Information, Knowledge, Wisdom



Adapted from: <http://blog.falkayn.com/2011/03/is-knowledge-all-there-is.html>

***«I know one thing: that I know nothing», Socrates***

# Smart Space-Based Resources Interaction in CPSS



# Smart Space



*Smart Space* – is a **computational environment** consisting of multiple heterogeneous **resources** (electronic and computational devices, Internet pages, data based, etc.) which has **intelligent behavior**, can **proactively** provide services taking into account **current situation** and meet the following properties:

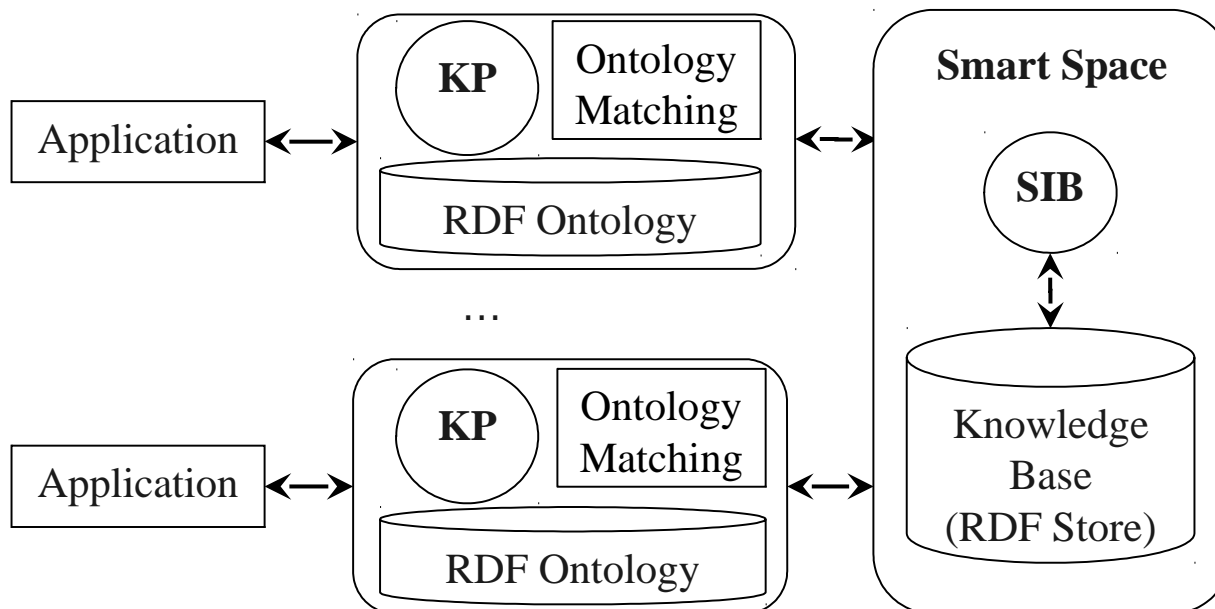
- Resources have to be **integrated in the space** or dynamically join and leave it.
- Resources have to provide **personalized user support**.
- Resources have to take into account **current situation**.
- Resources have to **be adaptive** (they have to respond to other devices and users actions).
- Resources have to provide **proactive behavior** (provide the user usefull at the moment services without explicit query).



# Smart-M3 Platform for Smart Space-Based Application Development



- Smart-M3 includes:
  - SIB: Devices and software entities (applications) **can publish their embedded information** for other devices and software entities through simple, shared Semantic Information Brokers.
  - The interface for managing information in the SIB is provided by Knowledge Processors (KP)
- The understandability of information is based on the usage of the **common RDF ontology** models and common data formats.



- Smart-M3 allows user KP to:
  - add,
  - remove,
  - change, and
  - subscribe,on information in SIB.

# Cyber-Physical-Social System Example: Home Cleaning Scenario



- Home cleaning scenario.
- Devices:
  - User Mobile Device (schedule, preferences)
  - Several vacuum cleaner robots (e.g. Yujin Robot iClebo Arte or iRobot Roomba)



- Several manipulating robots (e.g. FESTO Robotino XT)

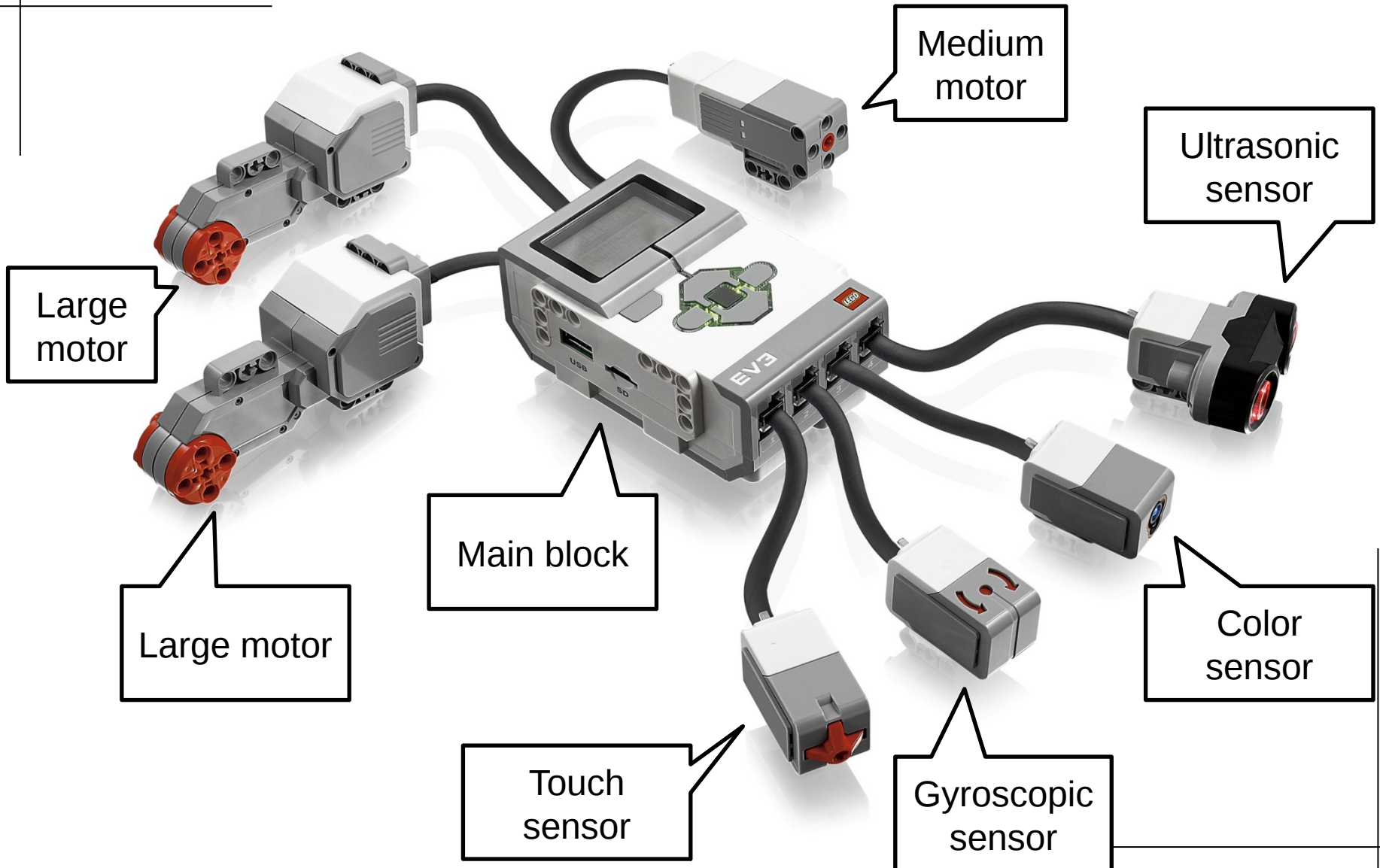
- “Smart home” systems (illumination control, information network, grid network, etc.)

# Home Cleaning Scenario: Two Simplified Scenarios

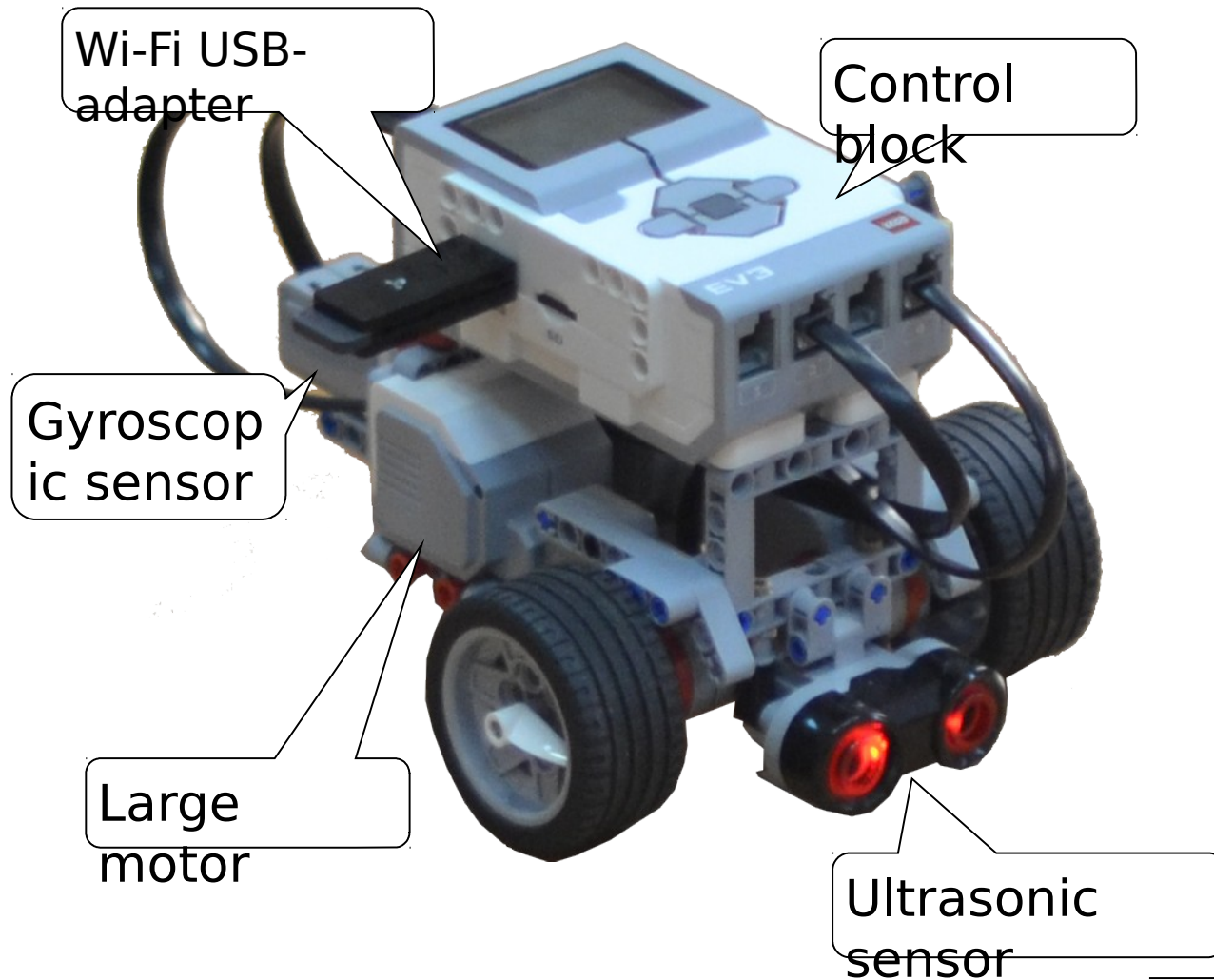


- Robots Interaction Scenario
  - Two or more robots receive a task to execute actions, e.g. find an object and bring it to a storage.
  - Only one robot should handle this task.
  - Robots should interact to find the one who will bring the object to the storage.
- Pick-and-Place Scenario
  - The system solves the task of pick-and-place an object from one point to another.
  - Two types of robots participate in the system scenario.
    - - Pipeline robot (can scan object's characteristics, can provide the object to the end of pipeline).
    - - Manipulating robot (can take the object and move it to another place based on object's characteristics).

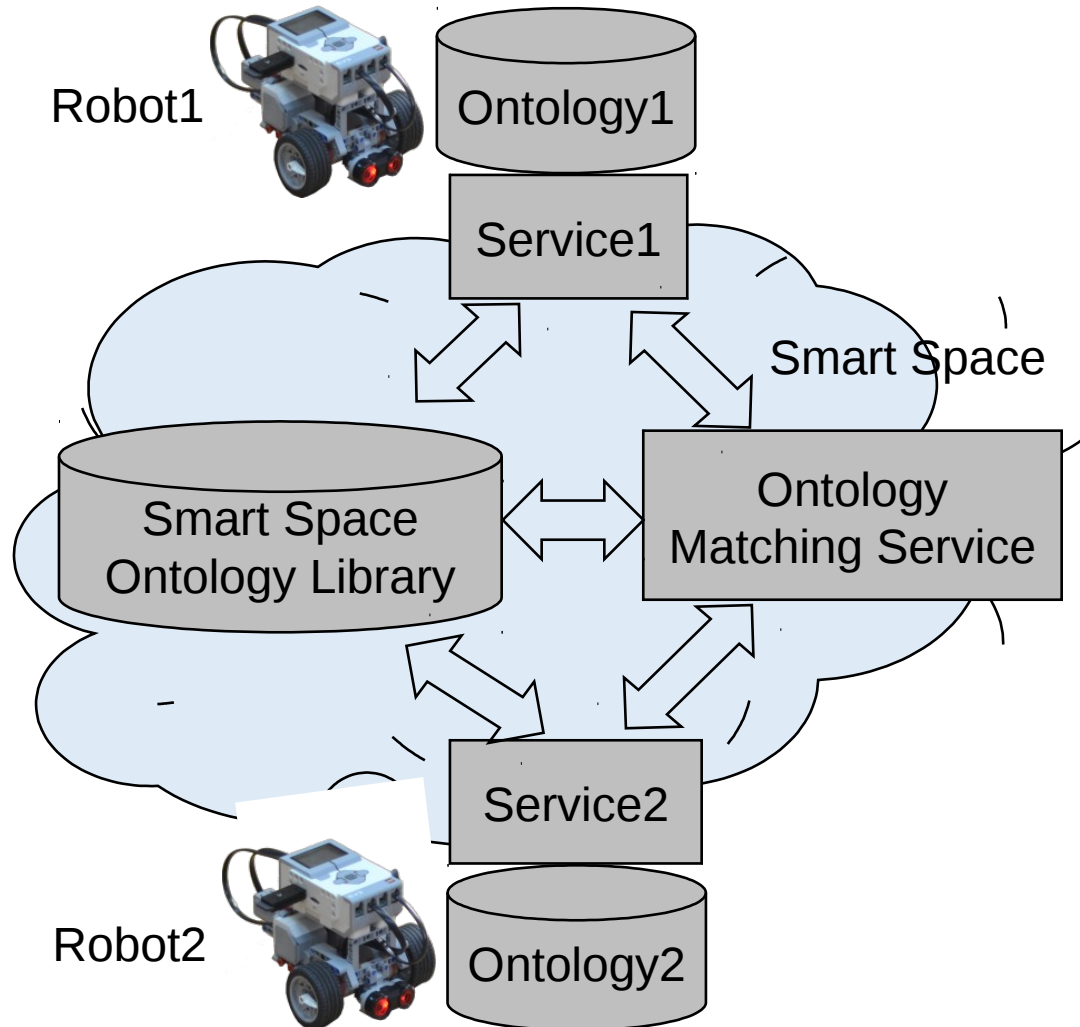
# LEGO® Mindstorms EV3 Kit



# Lego Mindstorms Robot Example



# Robot's Interaction in Smart Space Based on Ontology Matching





# Robots Interaction Scenario

## Live Demo

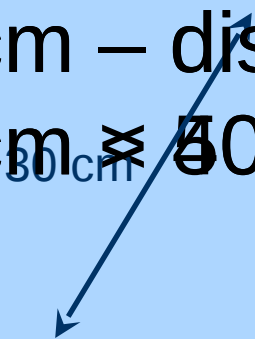


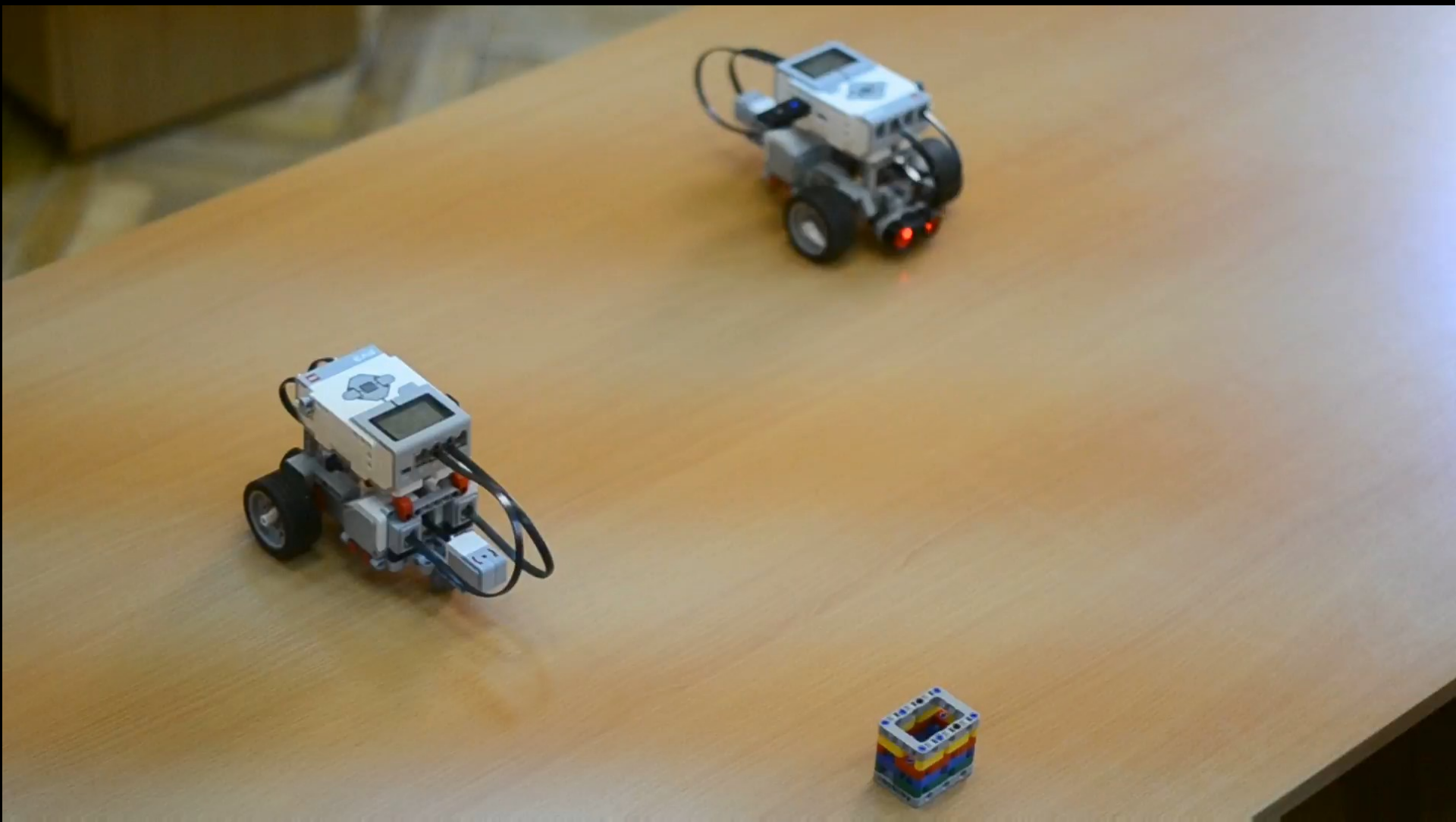
Robot 2:

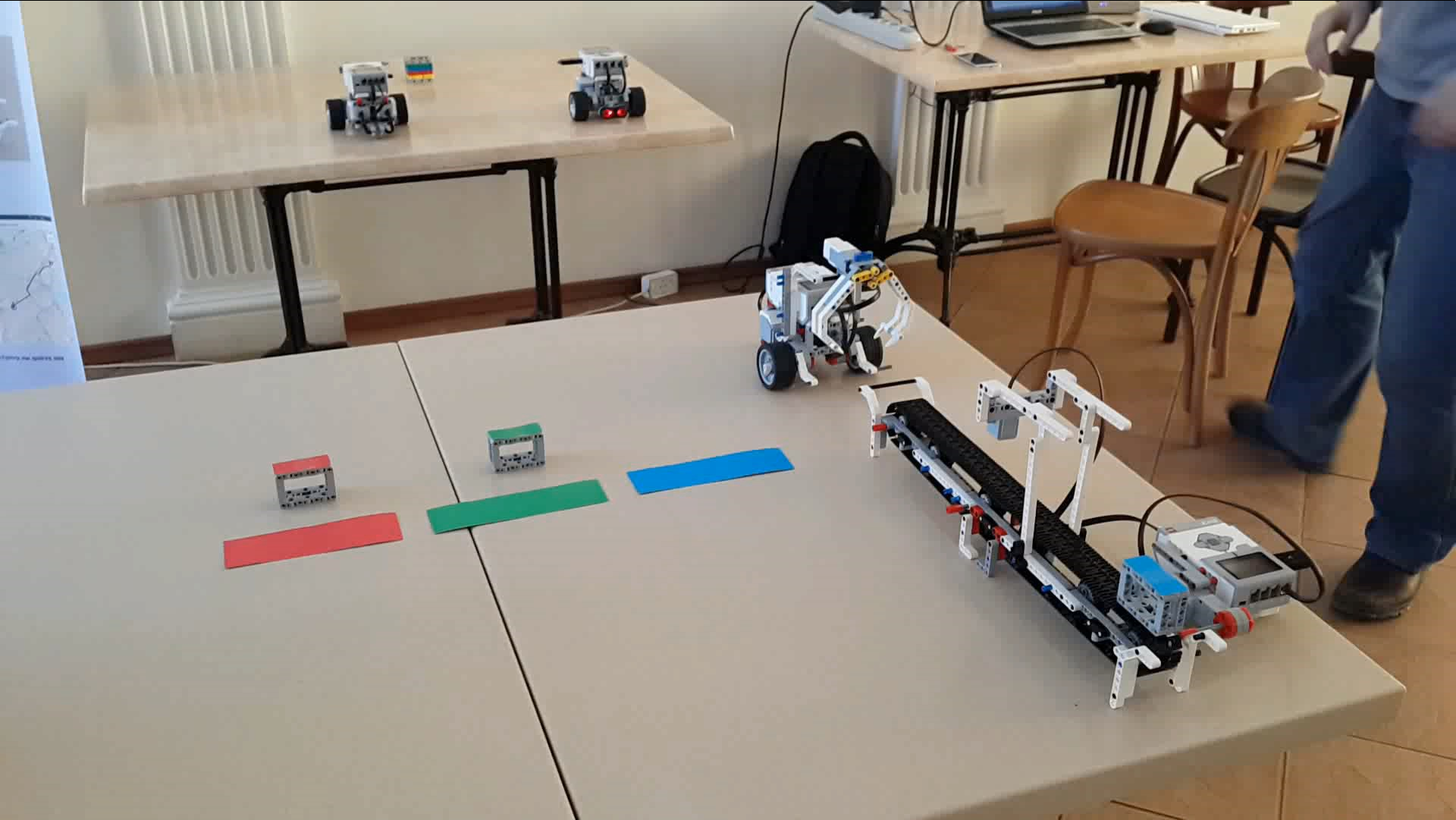
30 cm = 30 cm => It's another robot.

40 cm – distance to object.

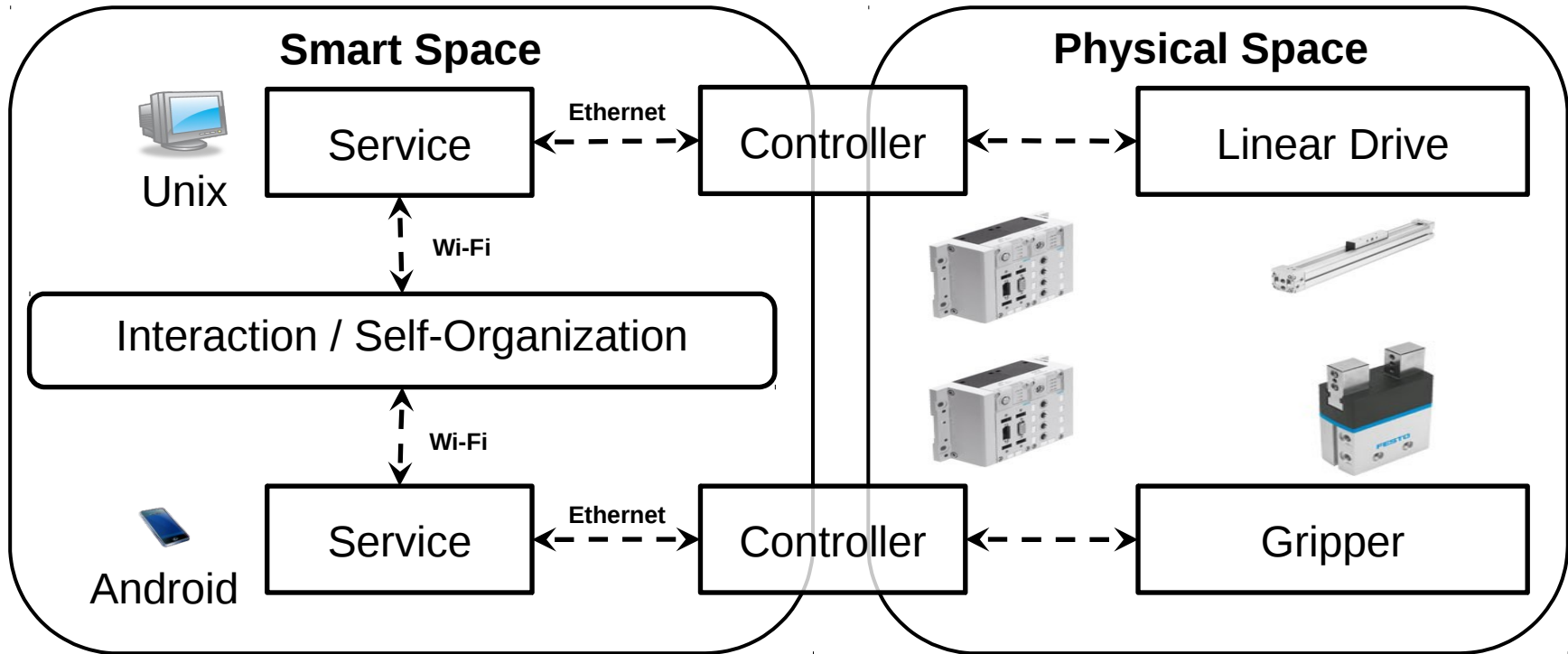
30 cm  $\approx$  40 cm => I have to stay here





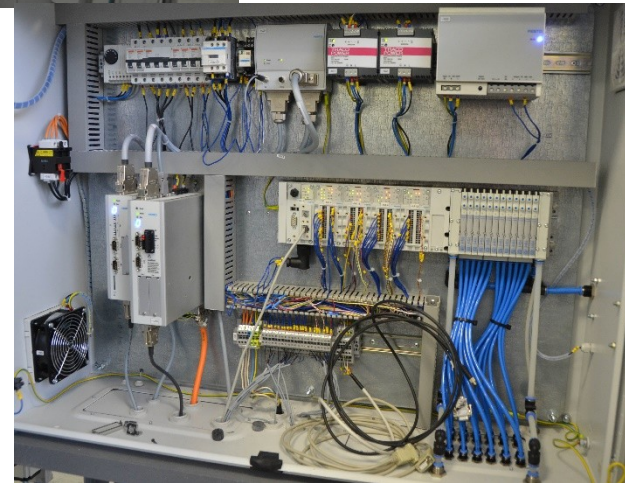
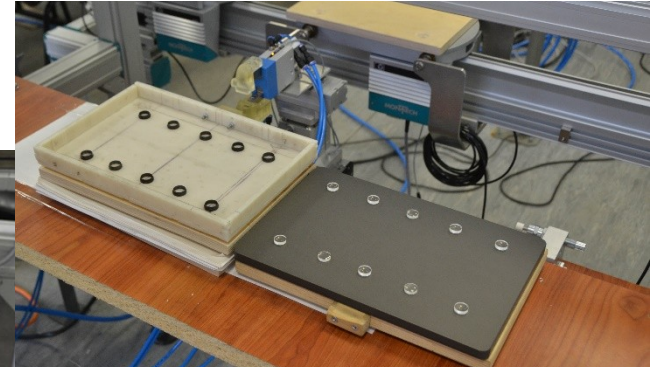
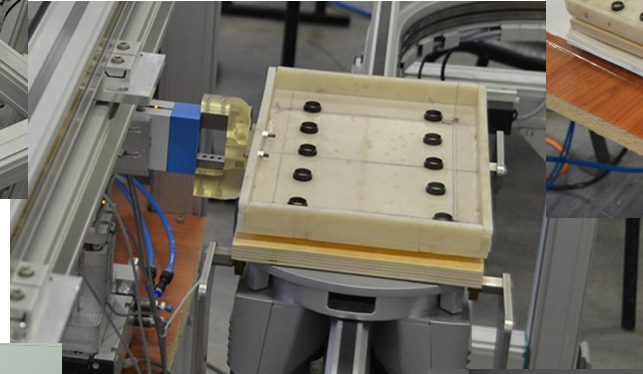
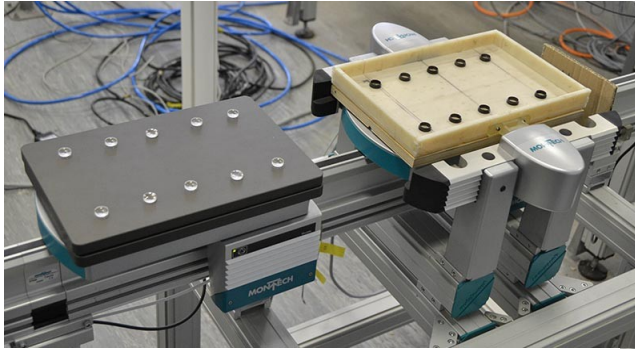


# Cyber-Physical Systems Example: Self-Organization in Industrial Systems

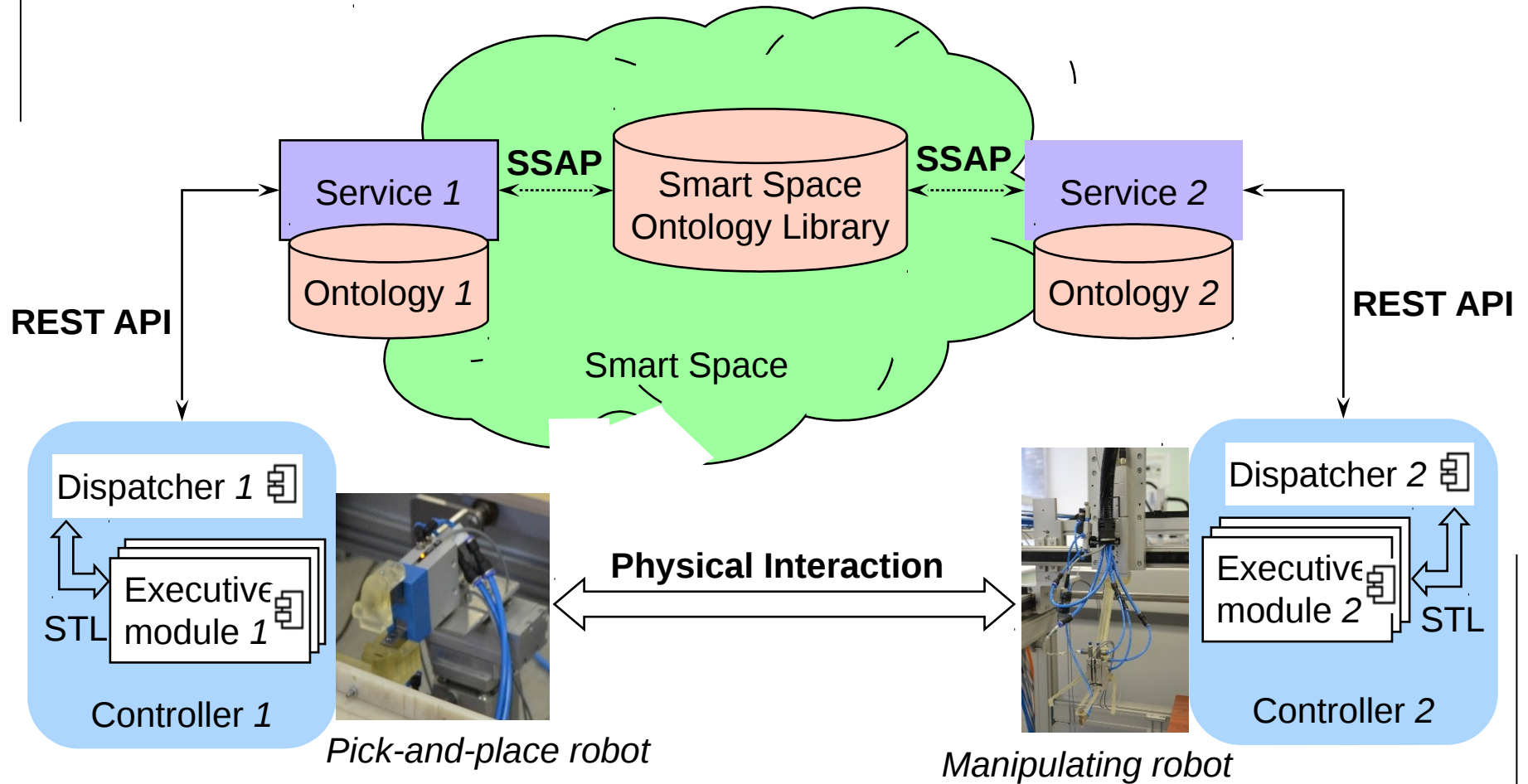




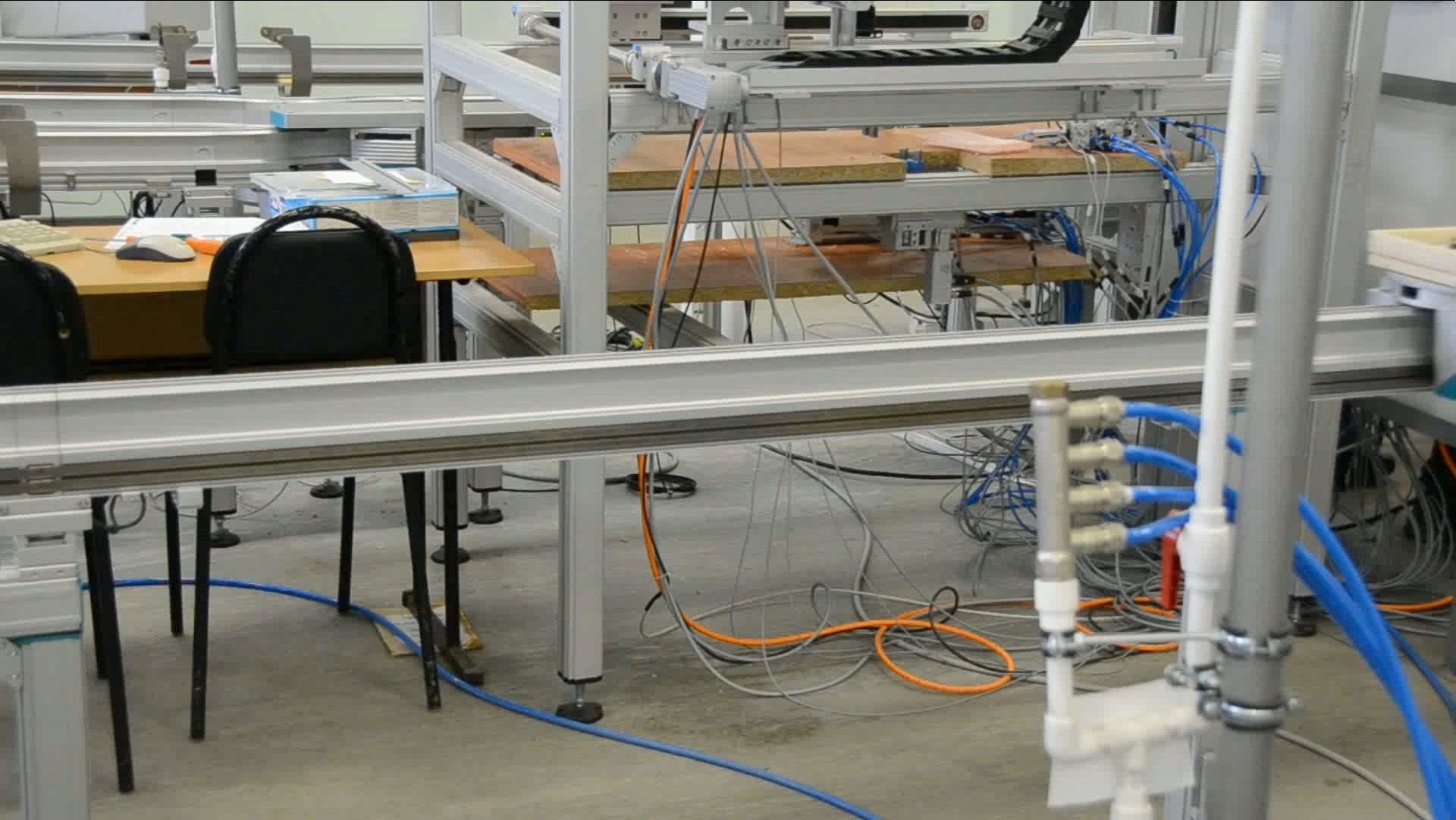
# Industrial Robots Interaction: Screenshots



# Industrial Robots Interaction in the Cyber-Physical System







Thank you for Attention  
Questions are Welcome



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