## Equilibrium in a P2P-system

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1. Case of two free-riders and one contributor



Player I's payoff if players make contributions  $x_1$  and  $x_2$  and contributor's contribution a is uniformly distributed in [0, 1].

$$H_1(x_1, x_2) = \begin{cases} \int_0^{x_1} a da - cx_1 = \frac{x_1^2}{2} - cx_1, & \text{for } x_1 < x_2 \\ \\ \int_{x_2}^{x_1} a da - cx_1 = \frac{x_1^2 - x_2^2}{2} - cx_1, & \text{for } x_1 > x_2 \end{cases}$$

Let player II uses the mixed strategy with propability density function  $g(x_2)$  in [b, 1] in such a way as to  $H_1(x_1, g(x_2)) = v$ , where v is a game value. In these conditions player I's payoff is:

$$H_1(x_1, g(x_2)) = \begin{cases} \frac{x_1^2}{2} - cx_1, & \text{for } x_1 < b \\ \frac{x_1^2}{2} - cx_1 - \frac{1}{2} \int_b^{x_1} x_2^2 g(x_2) dx_2, & \text{for } x_1 > b \end{cases}$$

$$\frac{\partial H_1(x_1, g(x_2))}{\partial x_1} = x_1 - c - \frac{x_1^2}{2}g(x_1) = 0.$$

and

$$g(x_1) = \frac{2}{x_1} - \frac{2c}{x_1^2}.$$

$$G(x) = \int g(x)dx = 2\ln x + \frac{2c}{x}(1-x) + 1$$
 (1.1)

$$G(b) = 0 \Rightarrow 2 \ln b + \frac{2c}{b}(1-b) + 1 = 0.$$
 (1.2)

The strategy G(x) is optimal if

$$H_1(x_1, g(x_2)) = x_1^2/2 - cx_1 < b^2/2 - cb \quad \forall x_1 < b.$$
 (1.3)



Using b = 2c in (1.2) we get condition for c:

$$\ln(2c) + 1 - c = 0 \Rightarrow c^* \approx 0.23196.$$
 (1.4)

Since game is symmetric we have prove

**Theorem 1:** Let  $c \in [0, c^*]$  where  $c^*$  is a root of (1.4). Then the optimal strategies of players are coincide and have form

$$G(x) = \begin{cases} 0, & \text{for } x < b \\ 2\ln x + \frac{2c}{x}(1-x) + 1, & \text{for } x \in [b, 1] \end{cases},$$

where *b* satisfies

$$2\ln b + \frac{2c}{b}(1-b) + 1 = 0$$

$$H_i(g,g) = b^2/2 - cb.$$

2. Case of two players and n contributors

$$H_1(x_1, x_2) = \begin{cases} n \int_0^{x_1} a da - cx_1 = n \frac{x_1^2}{2} - cx_1, & \text{for } x_1 < x_2 \\ n \int_{x_2}^{x_1} a da - cx_1 = n \frac{x_1^2 - x_2^2}{2} - cx_1, & \text{for } x_1 > x_2 \end{cases}$$

Let player II uses the mixed strategy with propability density function  $g(x_2)$  in [b, 1] in such a way as to  $H_1(x_1, g(x_2)) = v$ , where v is a game value. In these conditions player I's payoff is:

$$H_1(x_1, g(x_2)) = \begin{cases} n\frac{x_1^2}{2} - cx_1, & \text{for } x_1 < b \\ \\ n\frac{x_1^2}{2} - cx_1 - n\frac{1}{2}\int_b^{x_1} x_2^2 g(x_2) dx_2, & \text{for } x_1 > b \end{cases}$$

$$\frac{\partial H_1(x_1, g(x_2))}{\partial x_1} = nx_1 - c - n\frac{x_1^2}{2}g(x_1) = 0.$$

and

$$g(x_1) = \frac{2}{x_1} - \frac{2c}{nx_1^2}.$$

$$G(x) = \int g(x)dx = 2\ln x + \frac{2c}{nx}(1-x) + 1$$
 (2.1)

$$G(b) = 0 \Rightarrow 2 \ln b + \frac{2c}{nb}(1-b) + 1 = 0.$$
 (2.2)

The strategy (2.1) is optimal if

$$H_1(x_1, g(x_2)) = nx_1^2/2 - cx_1 < nb^2/2 - cb \quad \forall x_1 < b.$$
 (2.3)

Using b = 2c/n in (2.2) we get condition for c:

$$\ln(2c/n) + 1 - c/n = 0. \tag{2.4}$$

Since game is symmetric we have prove

**Theorem 2:** Let  $c \in [0, c^*]$  where  $c^*$  is a root of (2.4). Then the optimal strategies of players are coincide and have form

$$G(x) = \begin{cases} 0, & \text{for } x < b \\ 2\ln x + \frac{2c(1-x)}{nx} + 1, & \text{for } x \in [b, 1] \end{cases},$$

where *b* satisfies

$$2\ln b + \frac{2c(1-b)}{nb} + 1 = 0.$$

 $H_i(g,g) = nb^2/2 - cb.$ 

## 3. Case of m players and n contributors

for 
$$x < b$$
:  
 $H_1(x, g, \dots, g) = n \frac{x^2}{2} - cx$ 

for  $x \in [b, 1]$ :

$$H_1(x, g, \dots, g) = -cx + n \frac{x^2}{2} (\overline{G}(x))^{m-1}$$

$$+n\sum_{k=1}^{m-1} {m-1 \choose k} k(\overline{G}(x))^{m-1-k} \int_{b}^{x} g(t)(G(t))^{k-1} \frac{(x^{2}-t^{2})}{2} dt,$$
(3.1)

After some simplification we can rewrite (3.1) as

$$H_{1}(x, g, \dots, g) = -cx + n \frac{x^{2}}{2} (\overline{G}(x))^{m-1} + n \sum_{k=1}^{m-1} {m-1 \choose k} (\overline{G}(x))^{m-1-k} \int_{b}^{x} t(G(t))^{k} dt,$$
(3.2)

Since players use optimal strategies game value  $v = H_1(x, g, ..., g)$ for  $x \in [b, 1]$ . From  $\frac{\partial H_1(x, g, ..., g)}{\partial x} = 0$  we obtain

for b < x < 1 and  $\forall m \ge 2$ :

$$\frac{nx-c}{g(x)n(m-1)} = \frac{b^2}{2} (\overline{G}(x))^{m-2} + \int_b^x t(\overline{G}(x) + G(t))^{m-2} dt.$$
(3.3)

Consider the sequence of functions

$$s_k(x) = \frac{2}{x^2} \Big[ \frac{b^2}{2} (\overline{G}(x))^k + \int_b^x t(\overline{G}(x) + G(t))^k dt \Big], \quad \forall k = 1, 2, \dots, m-2,$$
(3.4)

which clearly satisfies

 $1 \equiv s_0(x) \ge s_1(x) \ge s_2(x) \ge \ldots \ge s_{m-2}(x) \ge 0, \quad \forall x \in [b, 1].$ 

Multiplying  $x^2/2$  on the both side of (3.4) and differentiating we get recurrential differential equation

$$\frac{2}{x}(1 - s_k(x)) - s'_k(x) = kg(x)s_{k-1}(x), \quad \forall k = 1, 2, \dots, m-2 \quad (3.5)$$

with boundary conditions

$$s_k(b) = 0, \quad \forall k = 1, 2, \dots, m-2.$$

By (3.3)-(3.4) we see

$$s_{m-2}(x) = \frac{2(nx-c)}{nx^2(m-1)g(x)}.$$

From above we obtain g(x)

$$g(x) = \frac{2(nx-c)}{nx^2(m-1)s_{m-2}(x)} \ge \frac{2(nx-c)}{nx^2(m-1)}.$$

We get b from

$$\int_{b}^{1} g(x)dx = 1.$$
 (3.6)

For optimality it is nesessary that  $nx_1^2/2 - cx_1 < nb^2/2 - cb$   $\forall x_1 < b$  or equivalent b > 2c/n. Using b = 2c/n in (3.6) we get condition for c:

$$\int_{2c/n}^{1} g(x)dx = 1.$$
 (3.7)

Hence we have prove

**Theorem 3:** Let  $c \in [0, c^*]$  where  $c^*$  is a root of

$$\int_{2c/n}^{1} g(x)dx = 1.$$

Also let  $\{s_1,\ldots,s_{m-2}\}$  is a solution of the system of differential equations

$$\frac{2}{x}(1-s_k(x)) - s'_k(x) = kg(x)s_{k-1}(x), \quad \forall k = 1, 2, \dots, m-2$$

with boundary conditions

$$s_k(b) = 0, \quad \forall k = 1, 2, \dots, m-2.$$

and

$$g(x) = \frac{2(nx-c)}{nx^2(m-1)s_{m-2}(x)}.$$

Let us choose b from condition  $\int_b^1 g(x) dx = 1$ . Then g(x) is an optimal strategy.

 $H_i(g,g,\ldots,g) = nb^2/2 - cb.$