

Regeneration Cycles Dependence in Confidence Estimation by Splitting

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Introduction

A confidence estimation of rare events probabilities in $M/G/1$ system is considered. We apply special speed-up simulation technique based on a combination of splitting and regenerative approach for the queue-size process. Besides, we consider an embedded Markov process instead of the original non-Markovian one.

A comparison with the known analytical results and with the Crude Monte-Carlo (CMC) simulation shows a high efficiency of the approach. In particular, a high precision is achieved much faster than by CMC that is crucial for the rare event simulation.

Problem

Consider the queue-size process $\{\nu(t), t \geq 0\}$ with a state space E in a $M/G/1$ queue with a Poisson input with the independent and identically distributed (i.i.d.) interarrival times $\{\tau_n\}$ with rate λ , the i.i.d. service times $\{S_n\}$ with distribution $B(x)$ and with a finite mean ES_1 .

A problem of rare event simulation is well known. We would like to estimate a *small stationary* probability

$$\gamma := P(\nu(t) \in A), \tag{1}$$

where $A \subset E$, $\gamma \approx 0$. So, following [11, 14], the event $\{\nu(t) \in A\}$ is called *rare event*, the set A is called *rare set*. Standard simulation (CMC) of γ requires enormous sample size to achieve a given accuracy, thus, the time of simulation is unacceptably huge. We seek to avoid this situation by using the technique of speed-up method Splitting [5, 7, 7].

In many cases, the estimates turn out to be unbiased [5, 7]. At the same time, it is equally important to prove also consistency and the applicability of a Central Limit Theorem (CLT) for confidence estimation.

In recent papers [2, 3], a modification of the splitting has been proposed which uses a correspondence between trajectories of a queueing Markov process obtained by the splitting and a regenerative structure. In turn, it justifies consistency of the estimate and allows us to apply regenerative simulation for confidence estimation of the (unknown) probability γ with a given precision [4, 9, 8, 15].

Regenerative interpretation

A standard spitting algorithm is typically used to estimate the (stationary) probability γ that the process hits a (rare) set A before reaching the state $\{0\}$, [5, 6, 7].

The state space E divided into $M + 1$ subsets, which defined by *importance function* f :

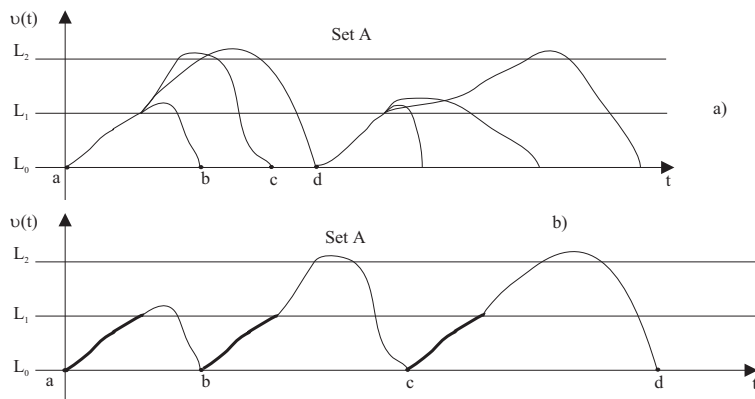
$$C_i = \{x \in E \mid f(x) \geq L_i\}, \quad i \in [1, M + 1],$$

$A = C_{M+1}$. The trajectory of the process splits at the predefined *thresholds* L_i only. The number of splits denoted by R_i , $R_{M+1} = 1$. The trajectory of the process is terminated upon reaching A (after hitting the threshold L_{M+1}).

For the standard Splitting, an optimal distance between thresholds and an optimal number of split paths at each threshold are known [5, 7]. It is necessary to note, that if the basic process is **Markovian** (for example, queue-size process in $M/M/1$ system) then the new trajectories are i.i.d (after splitting) and we can follow the [5, 7] for γ estimation.

But, in the case of **non-Markov process** (like continuous-time queue-size process in $M/G/1$ and $GI/G/1$ systems) the new trajectories (after splitting) are not longer independent, and it may be a source of an instability of the corresponding estimates [2].

We focus on regenerative interpretation of the method. As in a standard Splitting, we divide the state space E by $M + 1$ subsets C_i . But, we stop each path when the process hits zero state, and treat the obtained path as a regeneration cycle. Each trajectory started from L_0 gives the *bunch* of $D := R_1 \cdots R_{M+1}$ dependable regeneration cycles. The cycles from different bunches are independent by construction. The total number of bunches is the random variable R_0 .



Splitting for an embedded Markov chain

For the queue-size process in a non-Markov system $M/G/1$ we use the **embedded Markov chain method** [1]. We consider the process at the departure instants only (there is not a guarantee to split a trajectory exactly at each level L_i).

New splitting condition: *If a trajectory starting from a region $G(i) := C_i \setminus C_{i+1}$ (at a departure instant) crosses a threshold L_{i+k} , $i+k \leq M+1$, then it splits onto $\prod_{j=1}^k R_{i+j}$ paths ($R_{M+1} = 1$).*

The point estimator γ_{R_0} for γ is

$$\gamma_{R_0} = \frac{N_{M+1}}{R_0 \cdot D},$$

where N_{M+1} is the number of rare events.

Each trajectory now has a unique set of the thresholds to be split. Thus, there is a problem to obtain the optimal conditions for L_i, R_i as it was in standard Splitting.

Experimental results show the advantage of new algorithm expressed in variance reduction of point estimator for γ .

Confidence estimation

By using regenerative structure (given by splitting) and considering the dependences between the cycles in the bunch, we can now apply a regenerative simulation method [4, 8, 9, 10, 13, 15] for confidence estimation γ with the given precision.

Denote

$$Y_i := \sum_{j=(i-1) \cdot D+1}^{i \cdot D} I^{(j)}, \quad i = 1, \dots, R_0,$$

where $I^{(j)} = 1$ if the length of queue exceeds the level L_{M+1} at the regenerative cycle number j . Variables Y_i are i.i.d. The sequence $\{I^{(j)}\}_{j=1}^{D \cdot R_0}$ is regenerative with identical periods of regeneration equal to D .

From Regenerative Central Limit Theorem (RCLT) [15] under condition $EY_1^2 < \infty$ follows the expression of confidence interval for γ :

$$\left[\gamma_{R_0} \pm \frac{z_\delta \sqrt{\sum_{i=1}^{R_0} (Y_i - D \cdot \gamma_{R_0})^2}}{D \sqrt{R_0(R_0 - 1)}} \right], \quad (2)$$

where quantile z_δ satisfies $P(N(0, 1) \leq z_\delta) = 1 - \delta/2$. The point estimator γ_{R_0} defined by splitting procedure.

Results

Let the estimation precision be $x\%$ of γ (it means that the half of the interval length, given by (2), $\Delta = x\%$ of γ). Denote the half of interval without cycles dependence consideration by $\Delta_1 := \frac{z_\delta \sqrt{\gamma - \gamma^2}}{\sqrt{n}}$, where n the total number of regeneration cycles ($n = R_0 \cdot D$). The error that reflects the cost of dependence can be expressed as $y := \frac{(\Delta - \Delta_1)10^2}{\gamma}$.

Table 1.

#	γ	D	n	x	y	time (sec.)
1	2,92E-07	1	5,48E+07	49	0	21006,5
2	2,80E-07	10	2,86E+08	66,6472	44,7	10104,8
3	4,87E-07	100	1,55E+09	68,8478	61,7	5657,25
4	2,52E-09	5,03E+08	7,20E+13	47,7	47,2	77,265
5	3,80E-09	1,16E+09	7,65E+13	34,0	33,7	69,281
6	2,14E-09	2,37E+09	2,21E+14	21,9	21,7	152,593
7	1,57E-09	5,90E+09	5,89E+14	9,6	9,4	309,781
8	5,46E-09	3,28E+09	1,65E+14	6,1	5,9	352,89
9	2,46E-09	5,90E+09	4,69E+14	5,6	5,5	1023,39
10	2,34E-08	4,44E+09	1,66E+13	3,7	3,4	2550

The numerical results have confirmed that the dependence between regeneration cycles in the bunches (caused by dependence of trajectories having a common pre-history) essentially influences on interval length.

It is easy to see from Table 1 that $x \approx y$ (excepting the case of small D). Thus, it is impossible to consider the regeneration cycles from one bunch as independent. Otherwise the error coincides with accuracy.

The case $D = 1$ corresponds the CMC (in this case all cycles are independent), which gives error $y = 0$. Nevertheless, the CMC method is strongly loses on time in comparison with offered speed-up approach for confidence estimation with the given accuracy.

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